



OBE in Practice at FIBO

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ABOUT FIBO

Institute of Fleld roBOtics King Mongkut's University of Technology Thonburi

1 and only one in Thailand

and Automation, Master's degree in Technopreneurship.



All Faculty, Reseachers, and Engineers with **Robotics Expertises**

focused on Robotics for Productivity



Thailand's Center of Robotic Excellence

MISSIONS

> 200 research works

and academic services





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FIBO's Educational Approach



Motivation - The Will to Learn



Module System - Integrative Learning



Project based - Learning by Doing & Collaboration





Program Learning Outcomes - SILK



Self & Social Responsibility

- Self Respect
- Social
 Responsibility
- Professional Ethics



Integrative Thinking

- SystematicThinking
- Critical Thinking
- CreativeThinking
- Knowledge Integration



Lifelong Learning

- Intrinsic
 Motivation
- Self
 Development
- Perseverance



Knowledge & Skill

Technical K&S

- Mechanics
- Electronics
- Computer Science
- System Integration

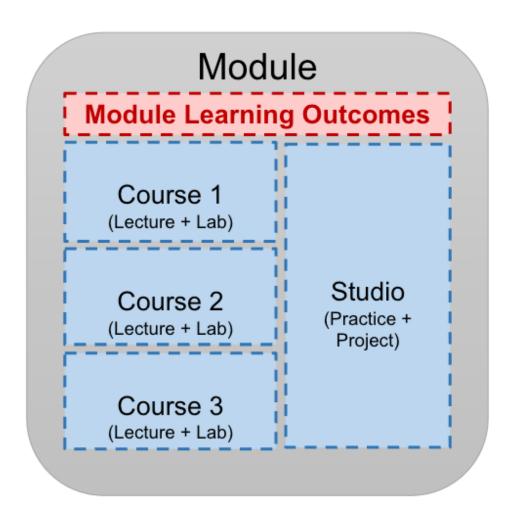
Professional K&S

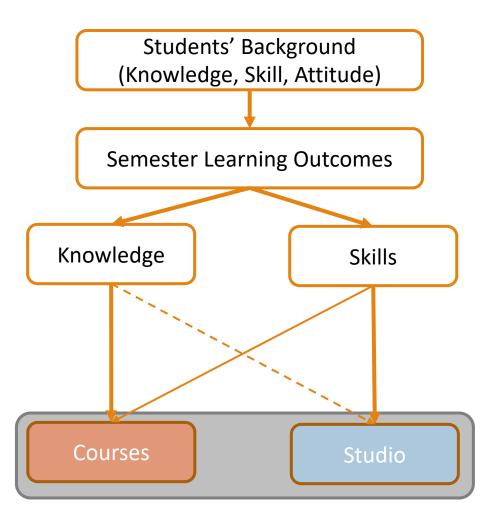
- Communication
- Teamwork
- Management
- Professionalism





Semester Structure









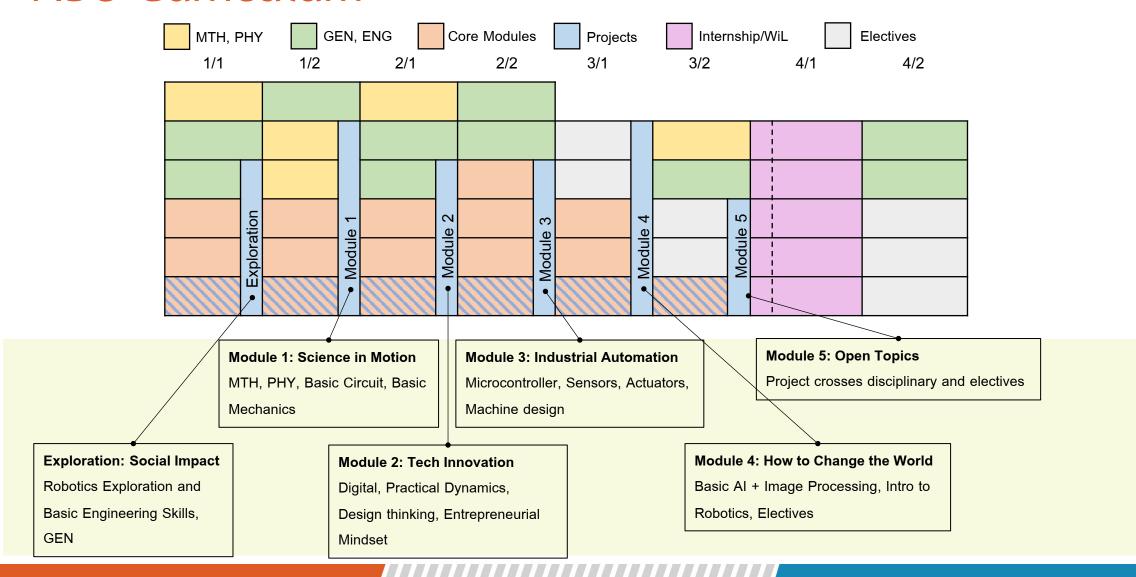
FIBO's Multi-layered Curriculum

Years	Knowledge & Skills	Career Path	Developments
1st – 2nd	Basic knowledge and skills	Career Exploration	Self-development
3rd - 4th	Advanced, personalized skills	Career Preparation	Societal impact





FIBO Curriculum

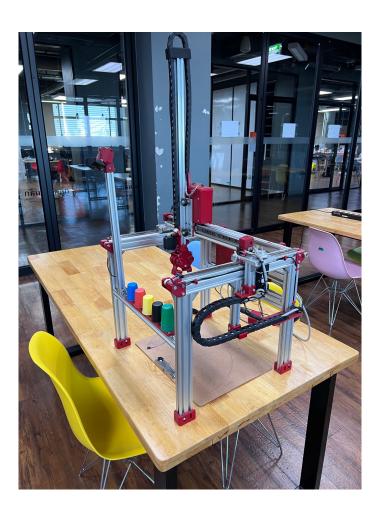


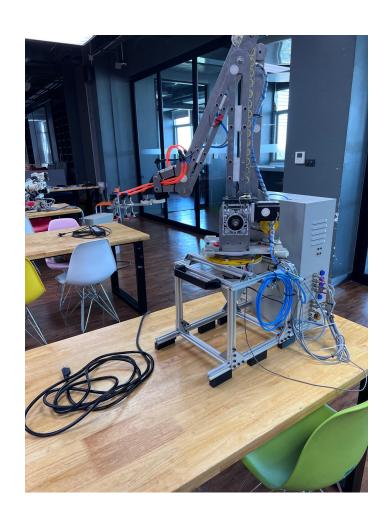




Module 0: Exploration





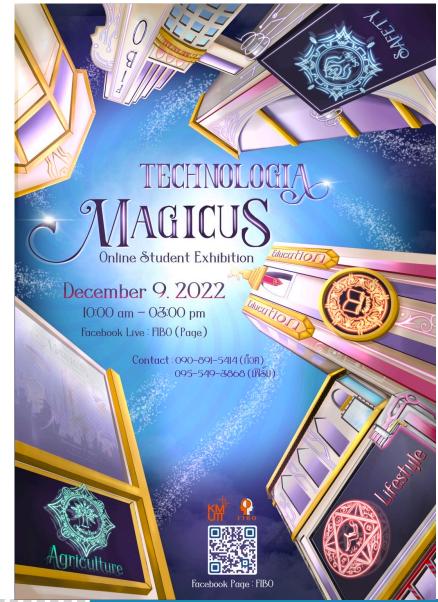






Module 0: Exploration



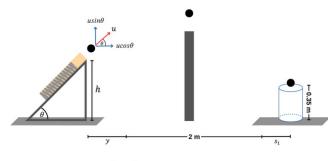






Module 1: Science in Motion

ขำนวณความเร็วของลูกสควอชหลังจากถูกปล่อยจากสปริง



พิจารณาการเคลื่อนที่ในแนวดิ่ง (แกน y)

พิจารณา
$$s_y = u_y t + \frac{1}{2} a t^2$$

โดยกำหนดให้
$$s_{v} = -h + 0.35 [m]$$

$$a = -9.8 \left[m/s^2 \right]$$

$$u_y = u sin\theta [m/s]$$

$$t = \frac{s_1 + y + 2}{u cos \theta} [s]$$

พิจารณาการเคลื่อนที่ในแนวระดับ (แกน x)

$$s_x = u_x t$$

โดยกำหนดให้ $s_x = s_1 + y + 2 [m]$

$$u_x = u cos\theta [m/s]$$

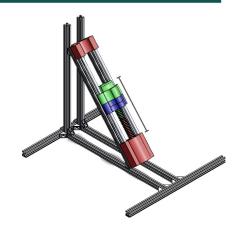
จะได้ว่า

$$t = \frac{s_1 + y + 2}{u cos \theta} [s]$$

จะได้ว่า

$$u = \sqrt{\frac{4.9(s_1 + y + 2)^2}{(h - 0.35 + tan\theta(s_1 + y + 2))\cos^2\theta}} [m/s]$$

CONCEPT DESIGN







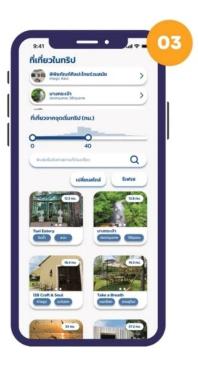


Module 2: Entrepreneurial Mindset

How to use



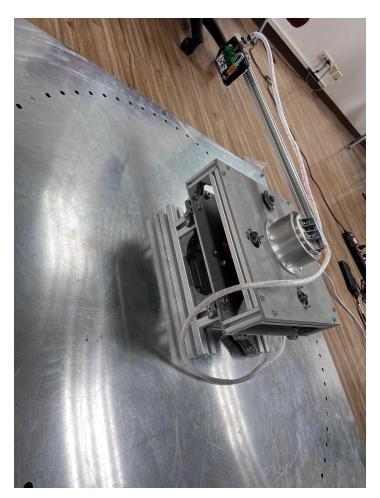


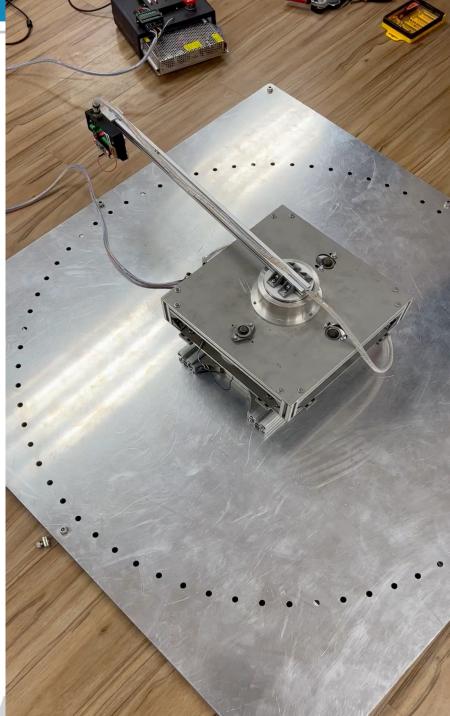




Module 3: Engineer's Path



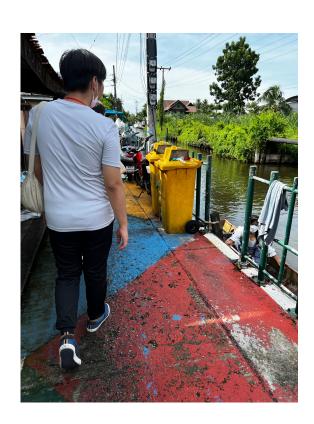


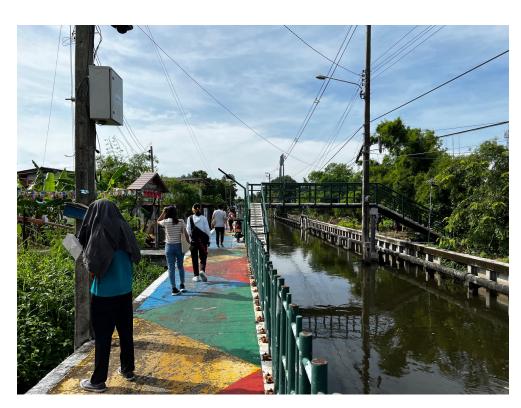


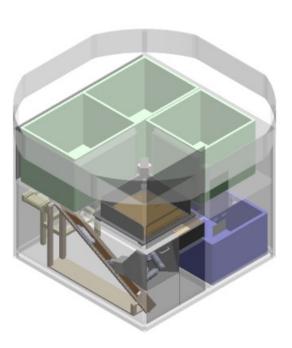


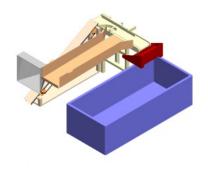


Module 4: How to Change the World











Contact Us

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A Cradle of Future Leaders in Robotics